



Anthropomorphe Multi-Agentensysteme: Simulation, Analyse und Steuerung (German Edition)

Christian Schlette

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„Anthropomorphe Multi-Agentensysteme“ erlauben die systematische und vereinheitlichte Simulation, Steuerung und Analyse vielfältiger komplexer Kinematiken in aktuellen Anwendungen von Robotertechnik in der Forschung und in der Industrie. Ein Schwerpunktthema von Christian Schlette ist die Simulation des menschlichen Bewegungsapparates, anhand derer zwei wesentliche Entwicklungsrichtungen verfolgt werden: Bei der ersten Entwicklungsrichtung demonstriert er am Beispiel eines „Virtuellen Menschen“, wie „Anthropomorphe Multi-Agentensysteme“ etablierte Basistechniken der Robotik geeignet erweitern und für die Adressierung komplexer Kinematiken rekombinieren. Diese Simulationen des „Virtuellen Menschen“ erlauben es ihm, menschliche Tätigkeiten nachzubilden und dabei insbesondere nach ergonomischen Kriterien zu analysieren. Darauf aufbauend demonstriert der Autor bei der zweiten Entwicklungsrichtung am Beispiel „Ergonomie“, wie auf Basis der „Anthropomorphen Multi-Agentensysteme“ ein neuartiger Methodentransfer ermöglicht wird – Methoden zur Simulation, Analyse und Steuerung des „Virtuellen Menschen“ werden auch für humanoide Roboter und anthropomorphe Mehrrobotersysteme bereitgestellt. Als Beispiel dieses Methodentransfers entwirft der Autor eine ergonomisch motivierte Bewegungssteuerung (und -planung), die für humanoide Roboter zu verbesserten, sehr menschenähnlichen Bewegungen führt.

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